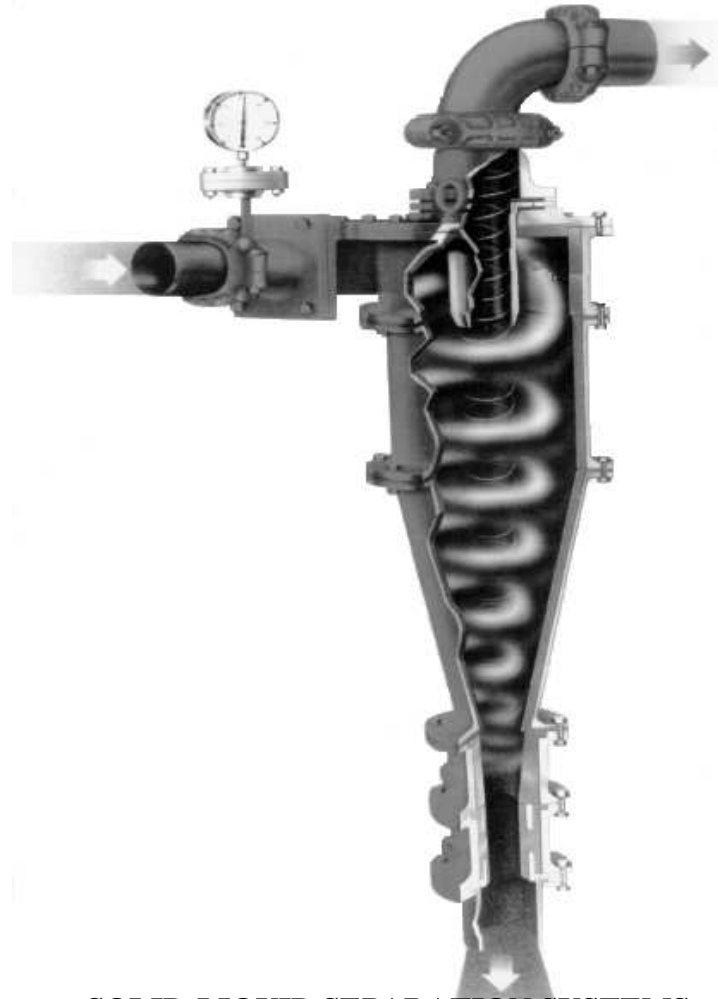


Numerical stability in the solution of the flow in an hydrocyclone

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The hydrocyclone



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Formulation: streamfunction - vorticity

☀ Velocity

$$\mathbf{u} \equiv (u, v, w)$$

☀ Vorticity

$$\mathbf{w} = \nabla \times \mathbf{v} \equiv (\xi, \eta, \zeta)$$

☀ Streamfunction

$$u = -\frac{1}{r} \frac{\partial \psi}{\partial z} \quad w = \frac{1}{r} \frac{\partial \psi}{\partial r}$$

☀ Circulation

$$\Gamma = vr$$

$$\nabla \cdot \mathbf{v} = 0$$

$$\frac{D\mathbf{v}}{Dt} = -\frac{1}{\rho} \nabla p + \nu \nabla^2 \mathbf{v}$$

$$\frac{D\mathbf{w}}{Dt} = \nabla \mathbf{v} \cdot \mathbf{w} + \nu \nabla^2 \mathbf{w}$$

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Formulation streamfunction – vorticity...

$$\frac{\partial \eta}{\partial t} = \frac{1}{r^3} \frac{\partial \Gamma^2}{\partial z} + \frac{u\eta}{r} - u \frac{\partial \eta}{\partial r} - w \frac{\partial \eta}{\partial z} + \nu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial}{\partial r} (r\eta) \right) + \frac{\partial^2 \eta}{\partial z^2} \right]$$

$$\frac{\partial \Gamma}{\partial t} = -u \frac{\partial \Gamma}{\partial r} - w \frac{\partial \Gamma}{\partial z} + \nu \left[r \frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial \Gamma}{\partial r} \right) + \frac{\partial^2 \Gamma}{\partial z^2} \right]$$

$$\eta = -\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial \psi}{\partial r} \right) - \frac{1}{r} \frac{\partial^2 \psi}{\partial z^2}$$

If $\beta = \eta/r$

$$\frac{\partial \beta}{\partial t} + u \frac{\partial \beta}{\partial r} + w \frac{\partial \beta}{\partial z} = \nu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \beta}{\partial r} \right) + \frac{2}{r} \frac{\partial \beta}{\partial r} + \frac{\partial^2 \beta}{\partial z^2} \right] + \frac{\partial}{\partial z} \left(\frac{\Gamma^2}{r^4} \right)$$

Formulation streamfunction – vorticity...

Advection-diffusion equation for a tracer c

$$\frac{\partial c}{\partial t} + \mathbf{v} \cdot \nabla c = \nu \nabla^2 c + f$$

If

$$\frac{\nu}{|\mathbf{v}|h} \ll O(1)$$

the standard numerical methods loose stability

Stabilized solution

- ✦ Solution using Finite Difference (Hsie, 1988)
- ✦ Our solution: use Finite Element
 - Boundary conditions are more direct
 - Use of complex and nonstructured meshes
 - A extension of USFEM method of Franca/Valentin (2000) for advective diffusive equations, using cylindrical coordinates

Stabilized solution...

Consider the differential equation

$$\mathcal{L}u = f$$

we to replace the variational for $(\mathcal{L}u, v) = (f, v)$
by the stabilized formulation

$$(\mathcal{L}u, v) - \sum_{K \in C_h} (\mathcal{L}u, \tau \mathcal{L}^\dagger v)_K = (f, v) - \sum_{K \in C_h} (f, \tau \mathcal{L}^\dagger v)_K$$

Stabilized solution...

where \mathcal{L}^\dagger is a discrete adjunct operator to \mathcal{L} ,

$$(\mathcal{L}u, v) = \int_{\Omega} \mathcal{L}(u)v d\Omega = \int_{\Omega} u\mathcal{L}^\dagger(v) d\Omega = (u, \mathcal{L}^\dagger v)$$

τ is a parameter depending on the element K of C_h

the terms that produce the stabilization contains functions that belong to the discrete space $V_h \subset H_0^1(\Omega)$.

Stabilized solution...

✿ Circulation equation

$$\dot{\Gamma} + \mathbf{a} \cdot \nabla \Gamma - \nu \left(\nabla^2 \Gamma - \frac{1}{r} \frac{\partial \Gamma}{\partial r} \right) = 0 \text{ in } \Omega \quad \mathbf{a} \equiv (u, w)$$

Discrete Galerkin formulation: find $u_h \in V_h$ such that

$$(\dot{u}_h, v_h) + (\mathbf{a} \cdot \nabla u_h, v_h) - \nu (\nabla^2 u_h, v_h) + \nu \left(\frac{1}{r} \frac{\partial u_h}{\partial r}, v_h \right) = 0, \forall v_h \in V_h$$

USFEM formulation: $(\dot{u}_h, v_h) + B(u_h, v_h) = 0, \forall v_h \in V_h$

$$B(u, v) = (\mathbf{a} \cdot \nabla u, v) + \nu (\nabla u, \nabla v) + 2\nu \left(\frac{1}{r} \frac{\partial u}{\partial r}, v \right) + \sum_{K \in \mathcal{C}_h} \left(\mathbf{a} \cdot \nabla u - \nu \Delta u + \frac{\nu}{r} \frac{\partial u}{\partial r}, \tau_K \left(\mathbf{a} \cdot \nabla v + \nu \Delta v + \frac{3\nu}{r} \frac{\partial v}{\partial r} + \frac{a_r v}{r} \right) \right)_K$$

Stabilized solution...

✚ Reduced Vorticity equation

$$\dot{\beta} + \mathbf{a} \cdot \nabla \beta - \nu \left(\nabla^2 \beta + \frac{3}{r} \frac{\partial \beta}{\partial r} \right) = f^{(\beta)} \text{ in } \Omega \quad \mathbf{a} \equiv (u, w)$$

Discrete Galerkin formulation: find $u_h \in V_h$ such that

$$(u_h, v_h) + (\mathbf{a} \cdot \nabla u_h, v_h) - \nu (\nabla^2 u_h, v_h) - 3\nu \left(\frac{1}{r} \frac{\partial u_h}{\partial r}, v_h \right) = (f^{(\beta)}, v_h), \forall v_h \in V_h$$

USFEM formulation: $(u_h, v_h) + B(u_h, v_h) = F(v_h), \forall v_h \in V_h$

$$B(u, v) = (\mathbf{a} \cdot \nabla u, v) + \nu (\nabla u, \nabla v) - 2\nu \left(\frac{1}{r} \frac{\partial u}{\partial r}, v \right) +$$

$$\sum_{K \in C_h} \left(\mathbf{a} \cdot \nabla u - \nu \Delta u - \frac{3\nu}{r} \frac{\partial u}{\partial r}, \tau_K \left(\mathbf{a} \cdot \nabla v + \nu \Delta v - \frac{\nu}{r} \frac{\partial v}{\partial r} + \frac{a_r v}{r} \right) \right)_K$$

$$F(v) = (f^{(\beta)}, v) + \sum_{K \in C_h} \left(f^{(\beta)}, \tau_K \left(\mathbf{a} \cdot \nabla v + \nu \Delta v - \frac{\nu}{r} \frac{\partial v}{\partial r} + \frac{a_r v}{r} \right) \right)_K$$

Stabilized solution...

Streamfunction equation

$$\beta r^2 = -\frac{\partial^2 \psi}{\partial r^2} - \frac{\partial^2 \psi}{\partial z^2} + \frac{1}{r} \frac{\partial \psi}{\partial r}$$

Standard Galerkin formulation:

$$(\beta r^2, v) = (\nabla \psi, \nabla v) + 2 \left(\frac{1}{r} \frac{\partial \psi}{\partial r}, v \right)$$

$$\nabla \equiv \left(\frac{\partial}{\partial r}, \frac{\partial}{\partial z} \right) \quad \nabla^2 \equiv \left(\frac{\partial^2}{\partial r^2}, \frac{\partial^2}{\partial z^2} \right)$$

Stabilized solution...

$$\tau_K = \frac{h_K^2}{6\nu \cdot \max\{Pe_K(\mathbf{x}), 1\}}$$

where

$$Pe_K(\mathbf{x}) = \frac{3|\mathbf{a}(\mathbf{x})|_2 h_K}{\nu}$$

$$|\mathbf{a}(\mathbf{x})| = \left(\sum_{i=1}^N |a_i(\mathbf{x})|^2 \right)^{\frac{1}{2}}$$

The formula for τ_K has a form that is suggested by static condensation, as explained in [7].



Integration in time

given

$$[A]\dot{\phi} + [B]\phi = [F]$$

the solution is

$$\phi^{t+\Delta t} = ([A] + \Delta t[B])^{-1}([A]\phi^t + [F]\Delta t)$$

Boundary conditions

☀ Walls ψ_o , ψ_u

☀ Inlet $\psi_o \leq \psi \leq \psi_u$

☀ Outlets $\frac{\partial \psi}{\partial n} = 0$

☀ Free surface $f \equiv Q_o/Q_u$ $f = \frac{\psi_o - \psi_{fs}}{\psi_{fs} - \psi_u}$

Boundary conditions...

✦ Dirichlet boundaries

$$[A]\{\psi\} = \{B\}$$

If ψ is known over m nodes belong to the contour Γ ,
 $\tilde{\Omega} \equiv \Omega - \Gamma$, we can split the vectorial space for ψ .

in two disjoint subspaces ψ_Γ and $\psi_{\tilde{\Omega}}$ in the form

$$\begin{bmatrix} A_{\Gamma\Gamma} & A_{\Gamma\tilde{\Omega}} \\ A_{\tilde{\Omega}\Gamma} & A_{\tilde{\Omega}\tilde{\Omega}} \end{bmatrix} \begin{Bmatrix} \psi_\Gamma \\ \psi_{\tilde{\Omega}} \end{Bmatrix} = \begin{Bmatrix} B_\Gamma \\ B_{\tilde{\Omega}} \end{Bmatrix}$$

the solution for $\psi_{\tilde{\Omega}}$ is

$$\psi_{\tilde{\Omega}} = A_{\tilde{\Omega}\tilde{\Omega}}^{-1}(B_{\tilde{\Omega}} - A_{\tilde{\Omega}\Gamma}\psi_\Gamma)$$

Results

☀ Turbulence: Prandlt model

$$\mu_t = K(R_e, \rho_m, \lambda(z, r), \mu_0) \left(\left| \frac{1}{r} \frac{\partial \Gamma}{\partial r} - \frac{2\Gamma}{r^2} \right| + \left| \frac{\partial w}{\partial r} \right| \right)$$

$$K = 0.01$$

☀ Simulation parameters

$$Re = 5.7 \times 10^5$$

$$dt = 0.01 \text{ seconds}$$

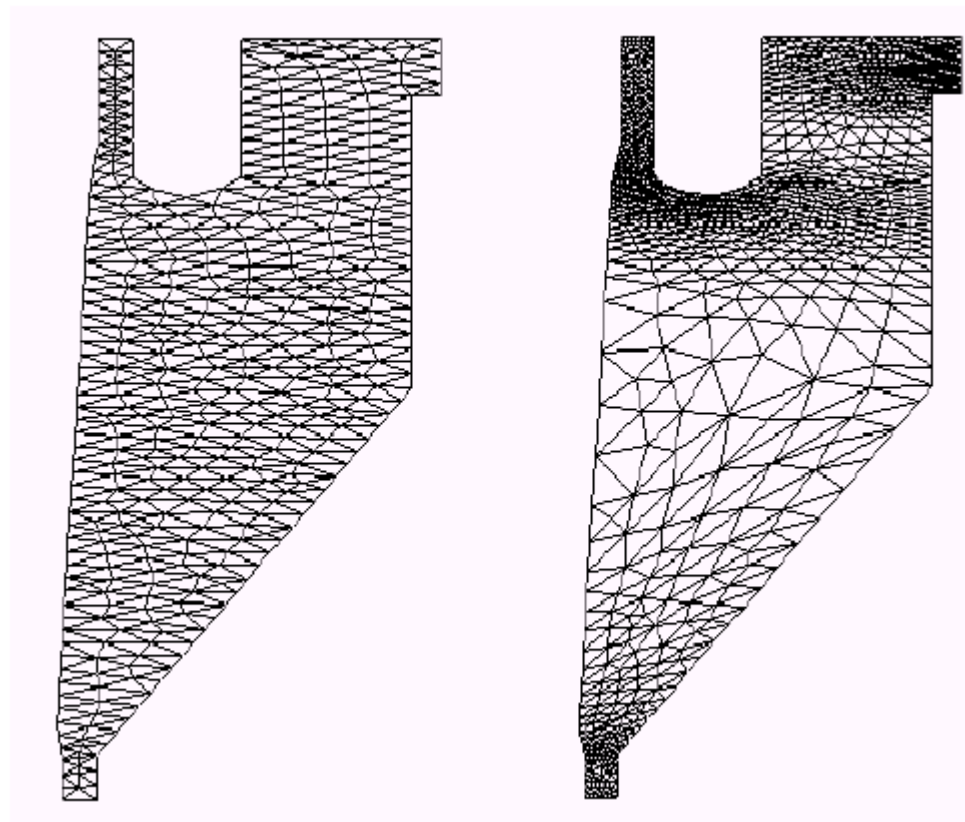
Results...

Dimension	cm.
Diameter hydrocyclone	50.80
Longitude cylindrical region	80.00
Feed diameter	13.13
Overflow diameter	11.43
Vortex diameter	26.67
Longitude vortex finder	31.80
Longitude conic region	116.80
Underflow diameter	6.35
<hr/>	
Operation variable	m^3/s
Feed flux	0.02348
Underflow flux	0.00643

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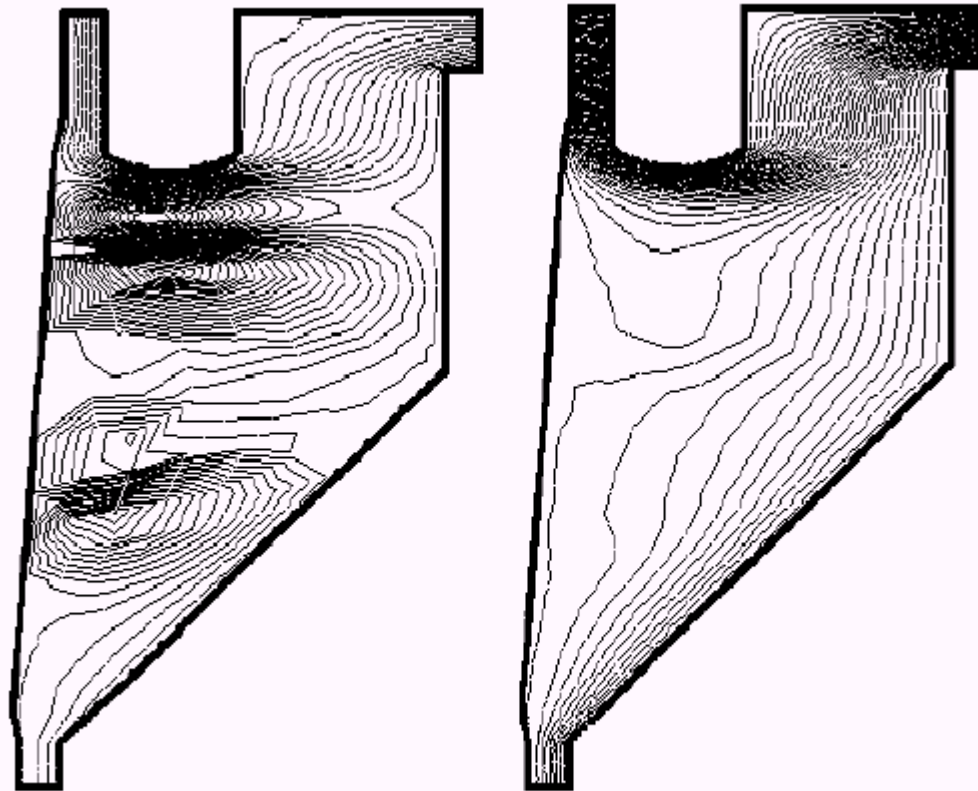
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Results...



Adapted mesh: 1109 points, 1987 triangles

Results...



Stream-function solution with and without stabilization scheme.

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Conclusions

- ✦ A stabilized FEM solution has been obtained using cylindrical coordinates on triangular adapted meshes
- ✦ The adjustment of the experimental form of a Rankine profile is obtained through a turbulence model